Cyber Security of Social Robots and the Internet of Things

Matthew Kinzler | Dr. Debbie Perouli | Marquette University

Purpose

The purpose of this research is to take the first steps in securing social robots against malicious activity.

Definitions

Social Robots - Robots designed specifically to interact with humans and other social robots



Internet of Things (IoT) - Devices that collect data and are accessible through the internet



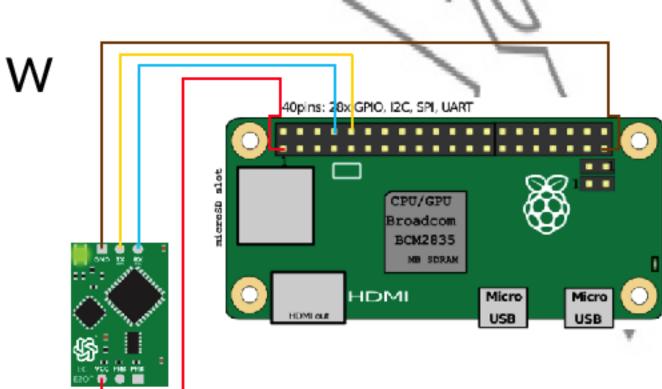
Source: www.computerweekly.com

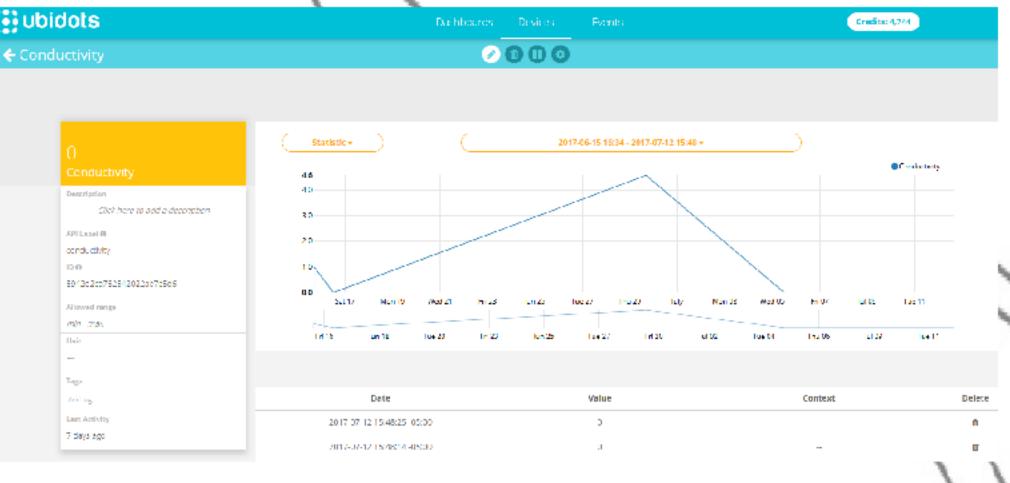
The Research Environment

Made by EZ-Robot

Source: www.solvelight.com

Raspberry Pi Zero W EZO Conductivity Circuit





password

social robot

help: What you see now

exit: CLI exit

scan: scan ap

version: Display hw/sw version

wifistate: Show wifi state

ifconfig: Show IP address

dns: show/clean/<domain>

memdump: <addr> <length>

memp: Print memp list

reboot: Reboot EZ-B

servo: Move a servo

time: Show system time

flash: Flash memory map

sockshow: Show all sockets

ugf: Start firmware upgrade

servospeed: Set Servo Speed

set: Set digital port state

bs: Show Highest Buffer Sizes

tasklist: List all thread name status

memset: <addr> <value 1> [<value 2> ... <value n>]

identify: Identify EZ-B with flashing LED and Audio Beep

memshow: Print memory information

wifidriver: Show wifi driver status

reset: Reset to default configuration

arp: arp show/clean

ping: ping <ip>

options

Uses Telnet (unencrypted) with no password

Results

Backup and retrieval to/from the cloud has

Login to Raspberry Pi requires username and

Established connection allows for extensive

Discovered security vulnerabilities related to the

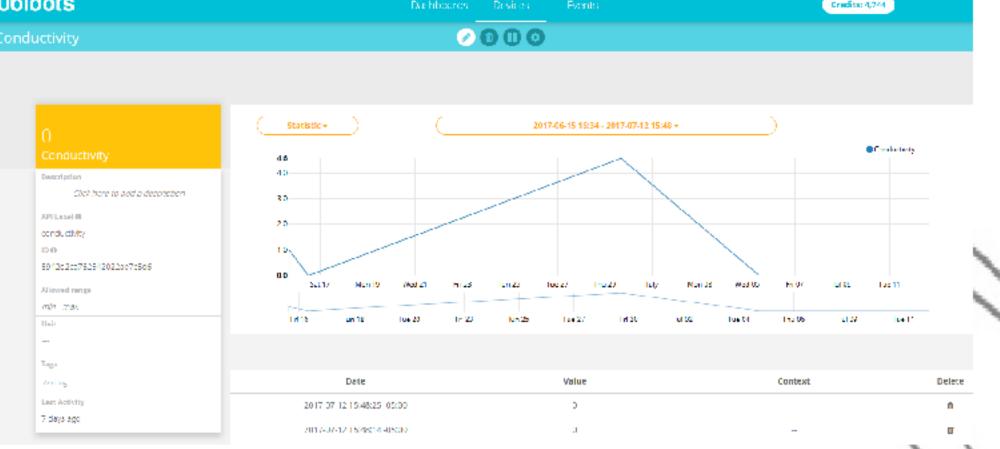
option for HTTPS (encrypted) protocol

- The programs run on the windows computer and send commands to the robot
- We strongly support the addition of an authentication mechanism implemented on the robot controller

Acknowledgements

Thanks to the National Science Foundation and the Marquette University Mathematics, Statistics, and Computer Science for providing the funding and infrastructure that allowed this research to be conducted.

- JD-Humanoid Robot



All of these devices are connected to each other through the cloud via Ubidots

Most Important References

- [1] Kali.org, 'Our Most Advanced Penetration Testing Distribution, Ever.', 2017. [Online]. Available: https://www.kali.org/ [Accessed 24 July 2017].
- [2]EZ-Bv4 Datasheet, EZ-Robot, 2016. [Online]. Available: https://www.ez-robot.com/Tutorials/Files/EZ-Bv4%20Datasheet.pdf. [Accessed 24 July 2017]
- [3]Denning, Tamara, et al. "A spotlight on security and privacy risks with future household robots: attacks and lessons." Proceedings of the 11th international conference on Ubiquitous computing. ACM, 2009



